

Vectors

(i) Level Surface:

- level surface generated by $f(x, y, z)$ are $f(x, y, z) = C$ [where C is arbitrary constant]

(ii) Level Curves:

- If $f(x, y)$ be a scalar function of two variables x, y then level curves generated by $f(x, y) = C$. [where C is arbitrary constant].

(iii) Position vectors of point in 3D = $(x\hat{i} + y\hat{j} + z\hat{k})$

$$\vec{r} = \text{p.v. of } (x, y, z) = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\Rightarrow \frac{d\vec{r}}{dt} = \text{velocity vectors} \quad \left| \quad \frac{d^2\vec{r}}{dt^2} = \text{Acceleration vectors} \right.$$

* Formula:

$$i) \frac{d}{dt} [\vec{c}] = 0, \text{ where } \vec{c} \text{ is constant vector}$$

$$ii) \frac{d}{dt} [k \vec{f}(t)] = k \frac{df(t)}{dt}, \text{ k is scalar [constant]}$$

$$iii) \frac{d}{dt} [\vec{u}(t) \pm \vec{v}(t)] = \frac{d\vec{u}}{dt} \pm \frac{d\vec{v}}{dt}, \text{ where, } \vec{u}, \vec{v} \text{ are vector function.}$$

$$iv) \frac{d}{dt} [\vec{u} \cdot \vec{v}] = \vec{u} \cdot \frac{d\vec{v}}{dt} + \frac{d\vec{u}}{dt} \cdot \vec{v}$$

$$v) \frac{d}{dt} [\vec{u} \times \vec{v}] = \vec{u} \times \frac{d\vec{v}}{dt} + \frac{d\vec{u}}{dt} \times \vec{v}$$

$$\text{(vii)} \quad \frac{d}{dt} [\vec{u} \cdot \vec{v} \cdot \vec{w}] = \left[\frac{d\vec{u}}{dt}, \vec{v}, \vec{w} \right] + \left[\vec{u}, \frac{d\vec{v}}{dt}, \vec{w} \right] + \left[\vec{u}, \vec{v}, \frac{d\vec{w}}{dt} \right]$$

$$\text{(vii)} \quad \frac{d}{dt} [\vec{u} \times (\vec{v} \times \vec{w})] = \frac{d\vec{u}}{dt} \times (\vec{v} \times \vec{w}) + \vec{u} \times \left(\frac{d\vec{v}}{dt} \times \vec{w} \right) + \vec{u} \times \left(\vec{v} \times \frac{d\vec{w}}{dt} \right)$$

$$\text{(viii)} \quad \frac{d}{dt} [\phi(t) \cdot \vec{u}(t)] = \phi(t) \frac{d\vec{u}}{dt} + \vec{u}(t) \frac{d\phi}{dt}$$

Note

If $\vec{r} = \vec{r}(t)$ be the eq. of some curve then $\frac{d\vec{r}}{dt}$ represent the direction of tangent vector.

* Gradient

$$\text{grad}(F) = \vec{\nabla} F = \left(\hat{i} \frac{d}{dx} + \hat{j} \frac{d}{dy} + \hat{k} \frac{d}{dz} \right) F$$

$$= \hat{i} \frac{dF}{dx} + \hat{j} \frac{dF}{dy} + \hat{k} \frac{dF}{dz}$$

→ It calculated for scalar function and after calculation it became vector function.

→ grad F is the rate of change of F.

→ [Geometrical]: grad F represent a normal vector to level curve, if $C(x, y) = C$

* Directional Derivative:

Let $F(x, y, z)$ be a scalar function then directional derivative of $F(x, y, z)$ in the direction of \vec{b} is given as $(\vec{\nabla} F) \cdot \hat{b}$ where \hat{b} is unit vector along \vec{b} .

→ Directional Derivative gives the rate of change of F in the direction of \vec{b} .

→ Maximum rate of change of any scalar valued function $F(x, y, z)$ is $|\vec{\nabla} F|$ and it occurs in the direction of $\vec{\nabla} F$.

→ Maximum rate of change of any scalar function $F(x, y, z)$ is $|\vec{\nabla} F|$ and it occurs in the direction of $-(\vec{\nabla} F)$ or opposite to $\vec{\nabla} F$.

* Divergence:

Let $\vec{v}(x, y, z)$ be a vector function, then divergence of $\vec{v}(x, y, z) = \text{div } \vec{v} = \nabla \cdot \vec{v} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z}$

$\vec{v} = v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}$

↳ divergence of \vec{v} as scalar function.

• $\vec{\nabla} \cdot \vec{v} \neq \vec{v} \cdot \vec{\nabla}$

↳ divergence ↳ operator

• Solenoidal vectors:

iff $\text{div } \vec{v} = 0$ then \vec{v} is solenoidal vector

* Curl

Let $\vec{v} = v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}$ be a vector function.

$$\text{Curl } \vec{v} = \vec{\nabla} \times \vec{v} = \hat{i} \times \frac{\partial v}{\partial x} + \hat{j} \times \frac{\partial v}{\partial y} + \hat{k} \times \frac{\partial v}{\partial z}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix}$$

$$\hat{i} \left[\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right] - \hat{j} \left[\frac{\partial v_3}{\partial x} - \frac{\partial v_1}{\partial z} \right] + \hat{k} \left[\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right]$$

Curl \vec{v} is a vector function.

Irrrotational vectors:

If $\text{Curl } \vec{v} = 0 \Rightarrow \vec{v}$ is irrotational vector.

Formula

(i) $\text{Curl}(\text{grad } \phi) = 0$, where ϕ is a scalar function.

(ii) $\text{div}[\text{Curl } \vec{v}] = 0$, where \vec{v} is a vector function.

(iii) $\text{div}[\phi \vec{u}] = \text{grad } \phi \cdot \vec{u} + \phi \text{div } \vec{u}$, where ϕ is scalar function and \vec{u} is vector function.

$$\Rightarrow \nabla \cdot [\phi \vec{u}] = \nabla \phi \cdot \vec{u} + \phi (\nabla \cdot \vec{u})$$

(iv) $\text{Curl}[\phi \vec{u}] = \text{grad } \phi \times \vec{u} + \phi \text{Curl } \vec{u}$

$$\Rightarrow \nabla \times [\phi \vec{u}] = \nabla \phi \times \vec{u} + \phi [\nabla \times \vec{u}]$$

$$\textcircled{\text{v}} \quad \text{div} [\vec{u} \times \vec{v}] = \vec{v} \cdot \text{curl} \vec{u} - \vec{u} \cdot \text{curl} \vec{v}$$

$$= [\vec{u} \times \vec{v}] \cdot \vec{0} = \vec{v} \cdot [\vec{v} \times \vec{u}] - \vec{u} \cdot [\vec{v} \times \vec{v}]$$

$$\textcircled{\text{vi}} \quad \text{curl} (\vec{u} \times \vec{v}) = (\vec{v} \cdot \nabla) \vec{u} - (\vec{v} \cdot \nabla) \vec{v} + \vec{u} (\nabla \cdot \vec{v}) - \vec{v} (\nabla \cdot \vec{u})$$

$$\textcircled{\text{vii}} \quad \text{grad} (\vec{u} \cdot \vec{v}) = (\vec{v} \cdot \nabla) \vec{u} + (\vec{u} \cdot \nabla) \vec{v} + \vec{v} \times \text{curl} \vec{u} + \vec{u} \times \text{curl} \vec{v}$$

$$\textcircled{\text{viii}} \quad \text{curl} (\text{curl} \vec{v}) = \text{grad} (\text{div} \vec{v}) - \nabla^2 \vec{v}$$

$$\nabla \cdot (\nabla \times \vec{v}) = \nabla \cdot [\nabla \cdot \vec{v}] - \nabla^2 v, \text{ where}$$

$$\nabla^2 = \frac{d^2}{dx^2} + \frac{d^2}{dy^2} + \frac{d^2}{dz^2}, \text{ Laplacian operator.}$$